Including multiple ground motion intensity measures in the derivation of Fragility Functions for Earthquake Loss estimation

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Abstract

This paper presents a methodology for the appropriate treatment of variability in the process of building vulnerability assessment. Material, geometric and mechanical properties of the assessed building typologies are simulated through a Monte-Carlo sampling procedure in which the statistical distribution of the latter parameters are taken into account. Record selection is performed in accordance with conditional hazard-consistent distributions of a comprehensive set of intensity measures, and matters of sufficiency, efficiency, predictability and scaling robustness are envisaged in the presented framework. Several intensity measures (IMs) are conjugated in the evaluation of building fragility and vulnerability, whereby fragility functions are established as the multivariate distribution of joint probability of being in a sequential set of damage states. Vulnerability Functions consequently determined provide not only a mean Damage Ratio per level of seismic intensity, but rather probabilistic distributions of Damage Ratio that reflect the ground motion variability expected as the interested site; as determined by the hazard-consistent conditional distribution of a set of sufficient intensity measures.

Subject Headings. Civil Engineering, Engineering Structure, Seismic Monitoring Author Keywords. Structural Capacity and Seismic Demand Variability, Ground Motion Selection, Nonlinear Dynamic Analysis, Hazard-Consistent Building Fragility and Vulnerability

1. Introduction

The premise that sources of aleatory variability (and its correlation) associated with groundmotion and structural response predictions cannot be neglected in loss assessment procedures has been demonstrated by several authors (e.g. Bazzurro and Luco, 2005). Hence, the purpose of this study is to evaluate and address the appropriate treatment of material, geometric and record-to-record variability in the evaluation of building fragility and vulnerability, whereby several *IMs* representing measures of spectral intensity, peak ground motion and spectral shape are considered throughout the stages of the proposed framework. Considerations of *efficiency* (Shome and Cornell, 1999), *sufficiency* (Luco, 2002), *scaling robustness* (Kramer and Mitchell, 2006) and *predictability* (Tothong and Luco, 2007) are thus foreseen in order to ensure the hazard consistent link between structural response and seismic demand.

The General Conditional Intensity Measure (*GCIM*) approach (Bradley, 2010a) is employed in the selection of natural ground motion records primarily scaled to match different levels of spectral ordinates at the assessed structures' fundamental period of vibration. According to

the latter, conditional distributions of a relevant set of *IMs* are determined taking into account all the rupture scenarios influencing seismic hazard at the interested site – Lisbon, Portugal – by means of the relative contribution established by disaggregation (Bazzurro and Cornell, 1999) of magnitude, distance and ground motion prediction models (*GMPE*), as formulated by Lin *et al.* (2013a).

Thousands of nonlinear dynamic analyses are performed within a probabilistic framework developed by Silva *et al.* (2014a), where hundreds of reinforced concrete distributed plasticity frame models are simulated in a 2D environment. Through Monte Carlo simulation, variability in geometric and material properties of typical two, five and eight-story pre-code reinforced concrete buildings in mainland Portugal is taken into account. Structural response is assessed in terms of engineering demand parameters (*EDP*) of peak global drift and inter-story drift, establishing the scope whereby seismic intensity and cumulative percentage of buildings in each damage state are related, by means of a function of multiple *IMs*.

2. Numerical Models

Following the work developed by Silva *et al.* (2014a), in which material and geometric properties of the most representative Portuguese building typologies were characterized, the numerical models considered herein represent typical buildings constructed before 1958 (pre - seismic code). Dynamic properties are characterized by mean fundamental periods of vibration equal to 0.26, 0.45 and 0.70 seconds, as a result from random generation of assets with respect to geometric and material statistical distributions of two, five and eight story buildings, respectively.

As demonstrated in a study by Silva *et al.* (2014b), in which a similar sampling framework was implemented, a number of one hundred assets is used to guarantee the statistically significance of the generated distribution of structural capacity. To keep the computational effort in a reasonable level, each structure is modelled as a single infilled frame with three bays, representing the assessed building's lateral load resisting system. Each frame was modelled in 2D environment, with force-based distributed plasticity elements formulation. For the sake of synthesis, considerations adopted with regard to: elements cross section discretization and integration points; material constitutive relationships; p-delta effects; and infill panels modelling approach, are referred to the aforementioned work by Silva *et al.* (2014a).

3. Record Selection Methodology

In the analytical assessment of building fragility and vulnerability, record-to-record variability is of upmost importance, given its influence in the estimated distribution of structural response (Lin *et al.*, 2013b). Amongst the available ground motion selection procedures that incorporate target mean and variance, the Generalized Conditional Intensity Measure (GCIM) approach proposed by Bradley (2010a) is adopted herein, whereby all the intensity measures identified as important to the outcome of the present exercise are foreseen.

It is proposed by the latter that for a given earthquake scenario, or rupture – Rup – any arbitrary vector of ground motion intensity measures – IM - has a multivariate lognormal distribution, to what follows that the distribution of IM given Rup (IM/Rup) conditioned on the occurrence of a particular level of a specific intensity parameter (IMj) - $f_{IMi|Rup,IMj}(im_i|rup_k, im_j)$ - presents identical statistical properties. In brief, since additional details shall be referred to the work of Bradley (2010a), upon definition of appropriate Ground Motion Prediction Equations (GMPE) and correlation structure between the different intensity

measures (*IMi*) in *IM*, the conditional distribution of each *IMi* given *IMj* = *imj* is obtained via total probability theorem from:

$$f_{IMi|IMj}(im_i|im_j) = \sum_{k=1}^{N_{Rup}} f_{IMi|Rup,IMj}(im_i|rup_k, im_j) P_{Rup|IMj}(rup_k|im_j)$$
(1)

Where $f_{IMi|IMj}(im_i|im_j)$ is the probability density function – pdf - of IMi given IMj=imj; $f_{IMi|Rup,IMj}(im_i|rup_k,im_j)$ is the pdf of IMi given IMj=imj and $Rup=rup_k$; and $P_{Rup|IMj}(rup_k|im_j)$ is the contribution weight of $Rup=rup_k$, determined through seismic hazard disaggregation. From the assumption that the IM vector is characterized by a multivariate lognormal distribution, it follows that for each IMi in IM, $f_{IMi|Rup,IMj}(im_i|rup_k,im_j)$ has a univariate lognormal distribution, which can be defined by its conditional mean and standard deviation parameters (Bradley, 2010a).

3.1. Probabilistic Seismic Hazard and Disaggregation

The use of tables within the text should be in a separate line. Each table should be numbered in the caption.

According to the findings of Vilanova *et al.* (2007), in which the applicability of different *GMPEs* to the Iberian region has been evaluated, the models developed by Atkinson and Boore (2006) and Akkar and Bommer (2010) are considered herein, with 0.70 and 0.30 logic tree weights, respectively, as defined in the hazard model implemented by Silva *et al.* (2014c).

Typically, causal earthquake magnitude, source-to-site distance and fault properties are considered in the definition of different scenarios – Rup – contributing to hazard in a given site, as established by disaggregation (Bazzurro and Cornell, 1999). However, following the findings of Lin *et al.* (2013a), seismic hazard disaggregation is evaluated in terms of Magnitude (*M*), Distance (*R*) and *GMPE*, in order to ensure the consistency between target distributions of all considered intensity measures - *IMi* - in *IM*, and the variability of ground motion properties expected at the interested site – Lisbon, Portugal. Thus, $f_{IMi|IMj}(im_i|im_j)$ presented above are estimated for each conditioning intensity level according to the contribution of all N_{Rup} scenarios and number of *GMPEs* considered:

$$f_{IM_{i}|IM_{j}}(im_{i}|im_{j}) = \sum_{m=1}^{N_{GMPE}} \sum_{k=1}^{N_{Rup}} f_{IM_{i}|Rup,IM_{j}}(im_{i}|rup_{k},im_{j},GMPE_{m})P_{Rup,GMPE_{m}|IM_{j}}(rup_{k},GMPE_{m}|im_{j})$$

$$(2)$$

The Openquake engine (Silva *et al.*, 2014d) which has been used for probabilistic seismic hazard analysis - considering rock site conditions (shear wave velocity in the top 30 m of the soil of 760 m/s) - does not currently address 3D disaggregation on *M*, *R* and *GMPE*; however, due to its open-source nature, it was possible to produce the necessary intermediate results for the computation of $P_{Rup,GMPE_m|IM_j}(rup_k, GMPE_m|im_j)$, as described herein:

$$P_{Rup,GMPE_m|IM_j}(rup_k,GMPE_m|im_j) = \frac{v(IM_j,Rup|GMPE_m).P(GMPE_m)}{v(IM_j)}$$
(3)

 $P(GMPE_m)$ stands for the logic-tree weight assigned to $GMPE_m$; $v(IMj, Rup|GMPE_m)$ is the rate corresponding to the conditional probability of IMj=imj, using $GMPE_m$, assuming a Poissonian process; and v(IMj) is the rate of occurrence of IMj=imj, computed from the correspondent rate of exceedance, as proposed by Bradley (2010a).

3.2. Selected Intensity Measures

As demonstrated in a study developed by Sousa *et al.* (2014), in which *efficiency* of an extensive set of *IMs* is evaluated in the context of fragility estimation of similar structures,

intensity measures incorporating velocity and spectral shape characteristics systematically provide higher correlations with damage exceedance probabilities. Any of such indicators can be considered in the *GCIM* selection; provided that *predictability* of marginal mean and standard deviation of the logarithm of each *IMi*, is ensured.

The applicability of the selected *GMPEs* to the specific case of mainland Portugal, previously addressed in this manuscript, render spectral acceleration at a range of periods as an obvious choice as target *IMs*. Thus, in order to ensure that target distributions computed for *IMs* other than spectral ordinates are consistent with the ground motion properties to be expected at the interested site, preference is given to *IMs* for which marginal median and logarithmic standard deviation can directly be determined or indirectly be inferred from the same *GMPEs*. Therefore, measures of peak ground acceleration, PGA, peak ground velocity, PGV, acceleration spectrum intensity, ASI, Housner intensity, HI; and spectral ordinates within the range of 0.05 to 3.0 seconds are considered; conditioned on *IMj* being the spectral acceleration at the assessed structures' fundamental period of vibration – *Sa*(*T*₁).

For each conditional Magnitude/ Distance / *GMPE*, median predications of *PGA* and *PGV*, along with the associated logarithmic standard deviations, can directly be obtained from the aforementioned *GMPEs*. As for the case of *ASI* and *HI*, since both intensity measures result from integrating spectral quantities in the period domain, target distributions can be computed based on the statistical parameters provided for distribution of spectral ordinates, as demonstrated by Bradley (2010b) and Bradley *et al.* (2009). The correlation models used for all the combinations of *IMs* considered are summarized in table 1.

	SA(Ti)	PGA	PGV	ASI	н
SA(Ti)	Baker and Jayaram (2008)	Baker (2007)	Bradley (2012)	Bradley (2011)	Bradley (2011)
PGA	-	-	Bradley (2012)	Bradley (2012)	Bradley (2011)
PGV	-	-	-	Bradley (2011)	Bradley (2012)
ASI	-	-	-	-	Bradley (2011)
н	-	-	-	-	-

Table 1: Correlation models considered for application of GCIM methodology

4. Fragility Assessment Framework

As discussed by Silva *et al.* (2014a), the use of local criterion to define limit states when generating fragility curves for population of buildings may not be appropriate. Hence, structural response conditioned on different levels of seismic intensity is evaluated in terms of maximum inter-story drift (*ISD*) and global drift (*GD*); defining thresholds of Slight Damage (*SD*), Moderate Damage (*MD*), Extensive Damage (*ED*) and Collapse (*Col*) limit states. *GD* limits are determined according to the evaluation of capacity performed through a displacement-based adaptive pushover (Antoniou and Pinho, 2004). Similarly to what has been considered by other authors, displacement thresholds at each limit state are defined for each sampled frame without masonry infills (bare frame) according to Silva *et al.* (2014a). The influence of infill panels, which is translated in a significant decrease of displacement capacity, is accounted for by applying the reduction factors proposed by Bal *et al.* (2010) for each limit state.

To what concerns *ISD*, a fixed set of values per limit state are defined based on the evaluation of global damage with increasing inter-story drift in 25 dynamic tests performed in real reinforced concrete moment resisting frames by Rossetto and Elnashai (2003). In order to adapt the damage scale proposed by the latter, which includes six levels, to the one presently

considered, *light / slight damage* and *partial collapse / collapse* limit states have been merged, as presented in Silva *et al.* (2014a).

4.1. Response Variability and Record selection

Since records are selected and scaled based on target distributions of a set of *IMs* that have distinct impacts on the spatial distribution of seismic demand, the number of ground motions required to achieve reasonable confidence in the estimated response's variability is not known *a priori*. It is recognized in the literature that a large number (greater than thirty) is necessary for the aforementioned purposes (e.g. Lin *et al.*, 2013b); nonetheless, an accurate estimate is highly dependent on the parameters used to characterize response, as well as the structural properties itself.

A number of 150 records, selected according to the *GCIM* methodology to match target distributions of the *IM* vector is hereby assumed as a sufficiently large sample to provide an accurate evaluation of inter-story drift (*ISD*) and global drift (*GD*) distributions at each level of conditional intensity measure - $Sa(T_1)$, in each sampled frame. The minimum number of records necessary to achieve identical distributions within a given statistical significance level can thus be determined by comparing the latter with responses resulting from record sets of increasing size, selected to match the same target *IM*. Accordingly, empirical distributions of *ISD* and *GD* obtained from samples of 10 to 140 records are individually compared with the *reference* sample of 150. This step is performed using the Brown–Forsythe (1974) (*BF*) test, according to which the hypothesis that two sets of data have equal variance is assessed at the 5% significance level, as illustrated in Figure 1.

Although only the results pertaining to 5 story frames and $Sa(T_1)$ equal to 1.0g are presented, the same conclusion is attained for samples of two and eight story frames, at all considered levels of conditioning seismic intensity parameter – $Sa(T_1)$. As also illustrated, a value of 60 records is considered to provide an adequate compromise between computational effort and statistical significance of results in terms of variance in distribution of Global Drift and Interstory Drift.



Figure 1: Ratio – p-value/alpha - between BF test statistic and corresponding significance level for 100 synthetic 5 story frames, when comparing distributions of response obtained from sets of 10 to 140 records, with the one obtained with the reference set of 150; records selected and scaled to a level of Sa(T1)=1.0g. Ratios equal or higher than 1.0 indicate that the null hypothesis of equal variance cannot be rejected at 5 % significance, for GD (left) and ISD (right)

4.2. Fragility Functions and Damage state probabilities

Fragility Functions typically describe the uncertainty in the capacity of a structural system (or a set of synthetically generated buildings, as in the present case), when subjected to sets of ground motion representing increasing values of seismic demand. In this context, it is possible to determine the uncertainty associated with the estimation of probabilities of exceeding specific damage states (for each level of primary intensity parameter - $Sa(T_1) = a$) through the convolution of the uncertain variables involved: seismic demand and structural capacity, as follows:

$$f\left[ds_{i|Sa(T_{1})=a}\right] = \int_{IM} F\left[ds_{i|IM,Sa(T_{1})=a}\right] \cdot f(IM_{|Sa(T_{1})=a}) \cdot dIM$$
(4)

Where $f\left[ds_{i|Sa(T_1)=a}\right]$ is the probabilistic distribution of probabilities of exceeding limit state i given $Sa(T_1)=a$; $F\left[ds_{i|IM,Sa(T_1)=a}\right]$ represents the structural capacity, as the probability of exceeding limit state i given IM and $Sa(T_1)=a$; $f\left(IM_{|Sa(T_1)=a}\right)$ is the probability density function of IM given $Sa(T_1)=a$; and IM is an intermediate variable that, representing the variability of seismic demand, allows separating the problem of explicitly determining the $f\left[ds_{i|Sa(T_1)=a}\right]$ distribution, as a conjunction of two uncertain variables: $F\left[ds_{i|IM,Sa(T_1)=a}\right]$ and $f\left(IM_{|Sa(T_1)=a}\right)$.

4.3. Conditional Fragility functions

As previously presented, *IM* is the vector of ground motion intensity measures considered in the process of record selection, for which the hazard consistent distribution given $Sa(T_1)=a - f(IM_{|Sa(T_1)=a})$ - is readily available. However, particular intensity measures are known to perform better in terms of correlation with damage when assessing similar structural typologies (Sousa *et al.*, 2014); leading to the further step of considering only the intensity measure – *IMi* - for which such correlation is higher (i.e. the most *efficient*), at each level of $Sa(T_1)$. Based on the latter assumption – whose validity is submitted to further investigations - that the most *efficient IMi* for each level of conditional intensity is *sufficient* to take into account all the explanatory variables in the *IM* vector; and given the fact that hazard consistent distributions of *IMi* given $Sa(T_1)=a - f(IMi_{|Sa(T_1)=a})$ - are equally determined in the process of record selection, the formulation presented in Equation 4 is updated, as follows:

$$f\left[ds_{i|Sa(T_{1})=a}\right] = \int_{IM_{i}} F\left[ds_{i|IM_{i},Sa(T_{1})=a}\right] \cdot f(IM_{i|Sa(T_{1})=a}) \cdot dIM_{i}$$
(5)

Where $F\left[ds_{i|IMi,Sa(T_1)=a}\right]$ translates the probability of exceeding a limit state *i*, as a function of *IMi*, when records are selected and scaled for a particular level of *Sa(T_1)*; hereby defined as a *conditional fragility function*.

As schematically presented in Figure 2, conditional fragility curves are evaluated upon the assumption that "record-specific" distributions of response follow a lognormal probabilistic function. Thus, by computing a distinct exceedance probability for each record, one can additionally assign to it the corresponding record specific value of *IMi*, establishing the conditional relationship between the variables; which enables the use of regression analysis to fit a lognormal cumulative distribution curve, as a function of *IMi*, conditioned on $Sa(T_1)=a$: $F\left[ds_{i_{|IM_i},Sa(T_1)=a}\right]$.



Figure 2: Record-specific distributions of response and corresponding probabilities of exceedance of Extensive Damage, determined according to ISD limit state criteria for 8 story frames (upper). Fitted conditional fragility curve, as a function of HI (lower). Records selected and scaled for Sa(T1)=1.0g

5. Propagation of uncertainty: from Fragility to Vulnerability

Given the fact that $f\left[ds_{i|Sa(T_1)=a}\right]$ (Equation 5) is an uncertain variable, it follows that the distribution of being exactly in a given damage state $i - p\left[ds_{i|Sa(T_1)=a}\right]$ - is also a random uncertain variant. As outlined in Equations 6 to 10, it can further be demonstrated that its variability is a function of *IMi*; of the uncertainty in the regression of $F\left[ds_{i|IM_i,Sa(T_1)=a}\right]$; and the correlation between uncertainties associated with $F\left[ds_{i|IM_i,Sa(T_1)=a}\right]$ at different limit states:

$$p\left[ds_{i|Sa(T_{1})=a}\right] = \int_{IM_{i}=0}^{+\infty} P\left[ds_{i|IM_{i},Sa(T_{1})=a}\right] \cdot f\left(IM_{i|Sa(T_{1})=a}\right) \cdot dIM_{i}$$
(6)

Where $P\left[ds_{i|IM_i,Sa(T_1)=a}\right]$ is the probability of being exactly in damage state *i*, conditioned on *IMi* and $Sa(T_1) = a$; as determined by following Equations 7 and 8:

$$P\left[ds_{i|IM_{i},Sa(T_{1})=a}\right] = F\left[ds_{i|IM_{i},Sa(T_{1})=a}\right] - F\left[ds_{i+1|IM_{i},Sa(T_{1})=a}\right]; 1 \le i \le N$$
⁽⁷⁾

$$P\left[ds_{i|IM_{i},Sa(T_{1})=a}\right] = F\left[ds_{i|IM_{i},Sa(T_{1})=a}\right]; i = N$$
(8)

In which N is the number of defined limit states and $F\left[ds_{i|IM_i,Sa(T_1)=a}\right]$ is the conditional probability of exceedance of limit state *i*, defined by the corresponding conditional fragility function.

According to the formulation above, it follows that the mean and variance of $p\left[ds_{i|Sa(T_1)=a}\right]$ depends on the mean and standard deviation of $F\left[ds_{i|IM_i,Sa(T_1)=a}\right]$, which, as subsequently

presented (and aforementioned), depends on the correlation between regression uncertainties associated with $F\left[ds_{i_{\mid IM_{i},Sa(T_{1})=a}}\right]$ at different limit states:

$$\mu_{P\left[ds_{i|IMi,Sa(T_{1})=a}\right]} = \mu_{F\left[ds_{i|IMi,Sa(T_{1})=a}\right]} - \mu_{F\left[ds_{i+1}|IMi,Sa(T_{1})=a\right]}$$
(9)

$$\sigma_{P[ds_{i|IMi,Sa(T_{1})=a}]}^{2} = \sigma_{F[ds_{i|IMi,Sa(T_{1})=a}]}^{2} + \sigma_{F[ds_{i+1}|IMi,Sa(T_{1})=a}]}^{2} - 2 \times$$

$$COV \left\{ F \left[ds_{i|IMi,Sa(T_{1})=a} \right], F \left[ds_{i+1}|IMi,Sa(T_{1})=a} \right] \right\}$$
(10)

Where $COV \left\{ F \left[ds_{i|IMi,Sa(T_1)=a} \right], F \left[ds_{i+1|IMi,Sa(T_1)=a} \right] \right\}$ is the covariance between distributions of damage exceedance probability for damage states *i* and *i+1*, conditioned on a particular level of *IMi* and *Sa(T1)=a*.

5.1. Combining sources of uncertainty

In order to completely define: a) the probabilistic distribution of $p\left[ds_{i|Sa(T_1)=a}\right]$; and b) $P\left[ds_{0|Sa(T_1)=a}, ds_{1|Sa(T_1)=a}, ds_{2|Sa(T_1)=a}, ds_{3|Sa(T_1)=a}, ds_{4|Sa(T_1)=a}\right]$, the joint distribution of damage probabilities; in which ds_0 to ds_4 refer to damage states of *No Damage (ND), SD, MD, ED* and *Col*, by the same order; Equations 6 to 10 are numerically solved through a Monte-Carlo simulation procedure, whereby a set of probabilities of being exactly in damage states of *ND, SD, MD, ED* and *Col* are computed for each simulation of *IMi* on the *dIMi* domain.

As illustrated in Figure 3, a bootstrap method has been used for computing a set of 500 conditional fragility curves, for each limit state. More importantly, each synthetic dataset has been primarily generated for the first limit state and the associated data points for the remaining limit states were selected in accordance with the latter. In these circumstances, it is possible to identify which conditional fragility curves - for limit states of *SD*, *MD*, *ED* and *Col* - correspond to which bootstrap simulation. Thus, for each Monte-Carlo simulation of *IMi* on the *dIMi* domain, 500 damage probabilities of *SD*, *MD*, *ED* and *Col* are jointly determined, according to Equations 7 and 8. The final result of the simulation procedure schematically presented in Figure 3 is thus a matrix of *M* x *N* dimension, in which *M* corresponds to the total number of simulations (1000 *MC* simulations times 500 bootstrap samples) and *N* refers to the number of damage state probabilities evaluated (*ND*, *SD*, *MD*, *ED* and *Col*). Therefore, the latter matrix constitutes a sampled approximation to the joint distribution of $P\left[ds_{0|Sa(T_1)=a'}ds_{1|Sa(T_1)=a'}ds_{2|Sa(T_1)=a'}ds_{3|Sa(T_1)=a'}ds_{4|Sa(T_1)=a}\right]$; hereby referred as "empirical simulated" joint distribution.

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Fragility functions are thus hereby established as the multivariate model of joint probability of being in damage states of *Slight Damage, Moderate Damage, Extensive Damage and Collapse*. Therefore, one can make use of the "empirical simulated" joint distribution; resorting to any appropriate Consequence Function to associate a Damage Ratio to each of the jointly simulated damage state probabilities. For illustration purposes, the Consequence Models proposed by Silva *et al.* (2014a), Bal *et al.* (2008) and FEMA-443 have been used. Damage ratio distributions are determined, according to the aforementioned methodology, for levels of $Sa(T_1)$ ranging from 0.1g to 1.0g, for 2, 5 and 8 story buildings; considering *Inter-Story* and *Global Drift* damage criteria; as depicted in Figure 4, for the case of *ISD*. Including multiple ground motion intensity measures in the derivation of Fragility Functions for Earthquake Loss estimation Luis Sousa, Vitor Silva, Mário Marques and Helen Crowley



The Vulnerability Functions consequently determined provide not only a mean damage ratio, but rather distributions of damage ratio per level of $Sa(T_1)$ that reflect the ground motion variability expected at the interested site for such level of intensity; as determined by the hazard-consistent conditional distribution of a *sufficient IMi*.

6. Conclusions

Variability in structural capacity has been properly addressed through a probabilistic approach towards the modelling of material, geometric and mechanical properties of two, five and eight story buildings constructed in Portugal before 1958 (pre-code). The Generalized Conditional Intensity Measure approach was adopted for the purpose of record selection, reflecting the variability of peak ground acceleration, PGA, peak ground velocity, PGV, acceleration spectrum intensity, ASI, Housner intensity, HI; and spectral ordinates within the range of 0.05 to 3.0 seconds, conditioned on increasing levels of spectral acceleration at the assessed structure's fundamental period of vibration.

Based on the appraised minimum number of ground motion records required to achieve reasonable confidence in the estimated responses' variability, the concept of *conditional fragility functions* has been introduced, translating the probability of exceeding a set of damage states as a function of a *sufficient IMi*, when records are selected and scaled for a particular level of the primary intensity measure: $Sa(T_1)$. In this context, *IMi* is an intermediate variable that, representing the variability of seismic demand, allows separating the problem of determining the distribution of damage exceedance probabilities, as a conjunction of two uncertain variables: structural capacity represented by the *conditional fragility function* and seismic action characterised by the hazard consistent distribution of *IMi*, conditioned on the interested level of $Sa(T_1)$.

Similarly, it has been demonstrated that the use of *IMi* as an intermediate variable allows the simulation of joint probabilities of being in a sequential set of damage states. Thus, Fragility

functions are hereby established as the multivariate model of joint probability of being in damage states of *Slight Damage, Moderate Damage, Extensive Damage and Collapse*. The latter allows the use of any *Consequence Function* to obtain Vulnerability functions characterized by distributions of *damage ratio* that reflect the uncertainty due to the ground motion variability expected at the interested site, for each level of primary intensity parameter $-Sa(T_1)$.

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